

PMR5406 Redes Neurais e Lógica Fuzzy

Aula 4 Radial Basis Function Networks

Baseado em:

Neural Networks, Simon Haykin, Prentice-Hall, 2nd edition

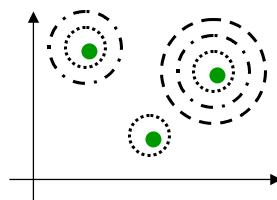
Slides do curso por Elena Marchiori, Vrije University

Radial-Basis Function Networks

- A function is approximated as a linear combination of radial basis functions (RBF). RBF's capture local behaviour of functions.

Biological motivation:

- RBF's represent local receptors:

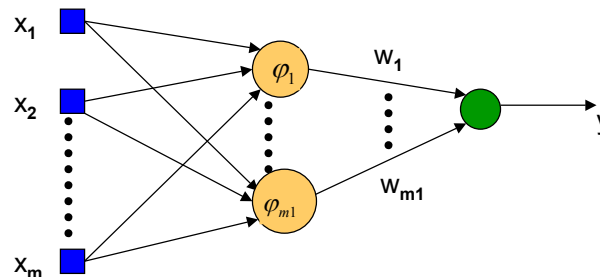


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ARCHITECTURE

- **Input layer:** source of nodes that connect the NN with its environment.



- **Hidden layer:** applies a **non-linear transformation** from the **input space** to the **hidden space**.
- **Output layer:** applies a **linear transformation** from the **hidden space** to the **output space**.

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ϕ -separability of patterns

$$\phi(x) = \langle \phi_1(x), \dots, \phi_{m_1}(x) \rangle$$

ϕ_i Hidden function

$\{\phi_i(x)\}_{i=1}^{m_1}$ Hidden space

A (binary) partition, also called **dichotomy**, (C_1, C_2) of the training set C is **ϕ -separable** if there is a vector w of dimension m_1 such that:

$$w^T \phi(x) > 0 \quad x \in C_1$$

$$w^T \phi(x) < 0 \quad x \in C_2$$

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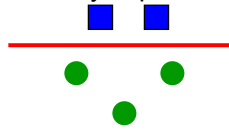
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Examples of ϕ -separability

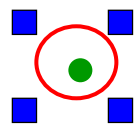
Separating surface: all x such that $w^T \phi(x) = 0$

Examples of separable partitions (C1,C2):

Linearly separable:

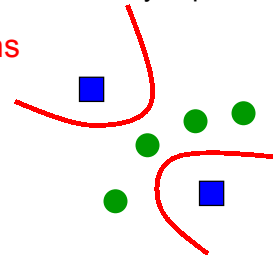


Polynomial type functions



Spherically separable:

Quadratically separable:



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Cover's Theorem (1)

size of feature space $\phi = \langle \phi_1, \dots, \phi_{m_1} \rangle$
 $P(N, m_1)$ - Probability that a particular partition (C1,C2) of the training set C picked at random is ϕ -separable

• **Cover's theorem.** Under suitable assumptions on $C = \{x_1, \dots, x_N\}$ and on the partitions (C1,C2) of C :

$$P(N, m_1) = \left(\frac{1}{2}\right)^{N-1} \sum_{m=0}^{m_1} \binom{N-1}{m}$$

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Cover's Theorem (2)

- Essentially $P(N, m_1)$ is a cumulative binomial distribution that corresponds to the probability of picking N points $C = \{x_1, \dots, x_N\}$ (each one has a probability $P(C_1)=P(C_2)=1/2$) which are ϕ -separable using m_1-1 or fewer degrees of freedom.

$$P(N, m_1) = \left(\frac{1}{2}\right)^{N-1} \left[\binom{N-1}{0} + \dots + \binom{N-1}{m_1-1} \right]$$

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Cover's Theorem (3)

- $P(N, m_1)$ tends to 1 with the increase of m_1 (size of feature space $\phi = \langle \phi_1, \dots, \phi_{m_1} \rangle$).
- More flexibility with more functions in the feature space $\phi = \langle \phi_1, \dots, \phi_{m_1} \rangle$

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Cover's Theorem (4)

- A complex pattern-classification problem cast in a high-dimensional space non-linearly is more likely to be linearly separable than in a low-dimensional space.

Corollary:

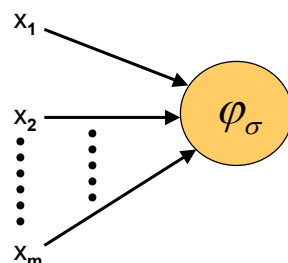
The expected maximum number of randomly assigned patterns that are linearly separable in a space of dimension m_1 is equal to 2^{m_1}

HIDDEN NEURON MODEL

- Hidden units: use a radial basis function

$$\varphi_{\sigma}(\|x - t\|^2)$$

the output depends on the distance of the input x from the center t



$$\varphi_{\sigma}(\|x - t\|^2)$$

t is called center

σ is called spread

center and spread are parameters

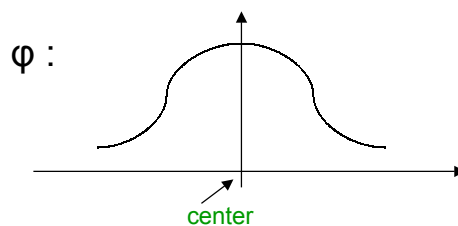
Hidden Neurons

- A hidden neuron is more sensitive to data points near its center. This sensitivity may be tuned by adjusting the spread σ .
- Larger spread \Rightarrow less sensitivity
- Biological example: cochlear stereocilia cells have locally tuned frequency responses.

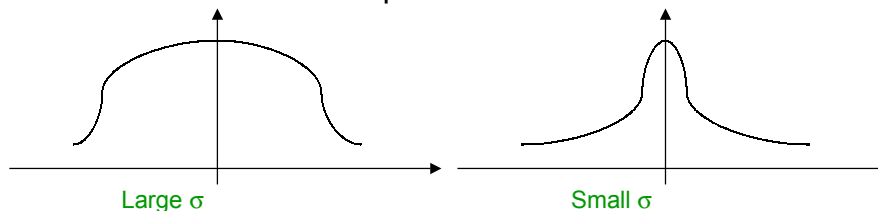
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Gaussian Radial Basis Function ϕ



σ is a measure of how spread the curve is:



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Types of φ

- **Multiquadrics:**

$$\varphi(r) = (r^2 + c^2)^{1/2} \quad c > 0$$

- **Inverse multiquadrics:**

$$\varphi(r) = \frac{1}{(r^2 + c^2)^{1/2}} \quad c > 0$$

- **Gaussian functions:**

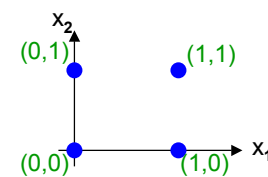
$$\varphi(r) = \exp\left(-\frac{r^2}{2\sigma^2}\right) \quad \sigma > 0$$

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Example: the XOR problem

- **Input space:**



- **Output space:**



- Construct an RBF pattern classifier such that:

(0,0) and (1,1) are mapped to 0, class C1

(1,0) and (0,1) are mapped to 1, class C2

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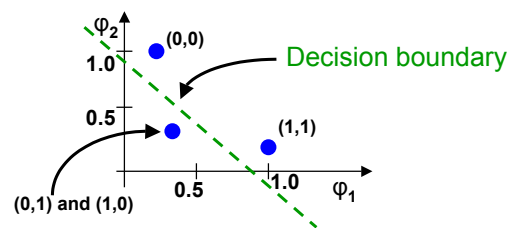
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Example: the XOR problem

- In the feature (hidden) space:

$$\varphi_1(x_1, x_2) = e^{-\|x-t_1\|^2} \quad t_1 = [1,1]^T$$

$$\varphi_2(x_1, x_2) = e^{-\|x-t_2\|^2} \quad t_2 = [0,0]^T$$



- When mapped into the feature space $\langle \varphi_1, \varphi_2 \rangle$, C1 and C2 become *linearly separable*. So a linear classifier with $\varphi_1(x)$ and $\varphi_2(x)$ as inputs can be used to solve the XOR problem.

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Learning Algorithms

- **Parameters** to be learnt are:
 - centers
 - spreads
 - weights
- Different learning algorithms

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Learning Algorithm 1

- **Centers are selected at random**
 - **center locations** are chosen randomly from the training set
- **Spreads are chosen by normalization:**

$$\sigma = \frac{\text{Maximum distance between any 2 centers}}{\sqrt{\text{number of centers}}} = \frac{d_{\max}}{\sqrt{m_1}}$$

$$\varphi_i(\|x - t_i\|^2) = \exp\left(-\frac{m_1}{d_{\max}^2} \|x - t_i\|^2\right)$$

$$i \in [1, m_1]$$

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Learning Algorithm 1

- **Weights** are found by means of **pseudo-inverse method**

$$W = \varphi^+ d \quad \begin{array}{l} \nearrow \text{Desired response} \\ \nearrow \text{Pseudo-inverse of } \varphi \end{array}$$

$$\varphi = \{\varphi_{ji}\} \quad \varphi_{ji} = \exp\left(-\frac{m_1}{d_{\max}^2} \|x_j - t_i\|^2\right)$$

$$j = 1, 2, \dots, N, i = 1, 2, \dots, m_1$$

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Learning Algorithm 2

- **Hybrid Learning Process:**
 - **Self-organized learning stage** for finding the centers
 - **Spreads** chosen by normalization
 - **Supervised learning stage** for finding the weights, using LMS algorithm

Learning Algorithm 2: Centers

- **K-means clustering algorithm for centers**

- 1 **Initialization:** $t_k(0)$ random $k = 1, \dots, m_1$
- 2 **Sampling:** draw x from input space C
- 3 **Similarity matching:** find index of best center

$$k(x) = \arg \min_k \|x(n) - t_k(n)\|$$

- 4 **Updating:** adjust centers

$$t_k(n+1) = \begin{cases} t_k(n) + \eta[x(n) - t_k(n)] & \text{if } k = k(x) \\ t_k(n) & \text{otherwise} \end{cases}$$

5. **Continuation:** increment n by 1, goto 2 and continue until no noticeable changes of centers occur

Learning Algorithm 3

- Supervised learning of all the parameters using the gradient descent method

– Modify centers

$$\Delta t_j = -\eta_{t_j} \frac{\partial E}{\partial t_j}$$

Instantaneous error function $\frac{1}{2} \sum_{i=1}^N e_i^2$

Learning rate for t_j

Depending on the specific function can be computed using the chain rule of calculus

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Learning Algorithm 3

- Modify spreads

$$\Delta \sigma_j = -\eta_{\sigma_j} \frac{\partial E}{\partial \sigma_j}$$

- Modify output weights

$$\Delta w_{ij} = -\eta_{ij} \frac{\partial E}{\partial w_{ij}}$$

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Comparison with multilayer NN

RBF-Networks are used to perform complex (non-linear) pattern classification tasks.

Comparison between **RBF networks** and **multilayer perceptrons**:

- Both are examples of *non-linear layered feed-forward* networks.
- Both are *universal approximators*.
- Hidden layers:
 - **RBF networks** have one *single* hidden layer.
 - **MLP networks** may have *more* hidden layers.

Comparison with multilayer NN

- Neuron Models:
 - The computation nodes in the hidden layer of a RBF network are *different*. They serve a different purpose from those in the output layer.
 - Typically computation nodes of MLP in a hidden or output layer share a *common neuron model*.
- Linearity:
 - The hidden layer of RBF is *non-linear*, the output layer of RBF is *linear*.
 - Hidden and output layers of MLP are usually *non-linear*.

Comparison with multilayer NN

- Activation functions:
 - The argument of activation function of each hidden unit in a RBF NN computes the *Euclidean distance* between input vector and the center of that unit.
 - The argument of the activation function of each hidden unit in a MLP computes the *inner product* of input vector and the synaptic weight vector of that unit.
- Approximations:
 - RBF NN using Gaussian functions construct *local* approximations to non-linear I/O mapping.
 - MLP NN construct *global* approximations to non-linear I/O mapping.